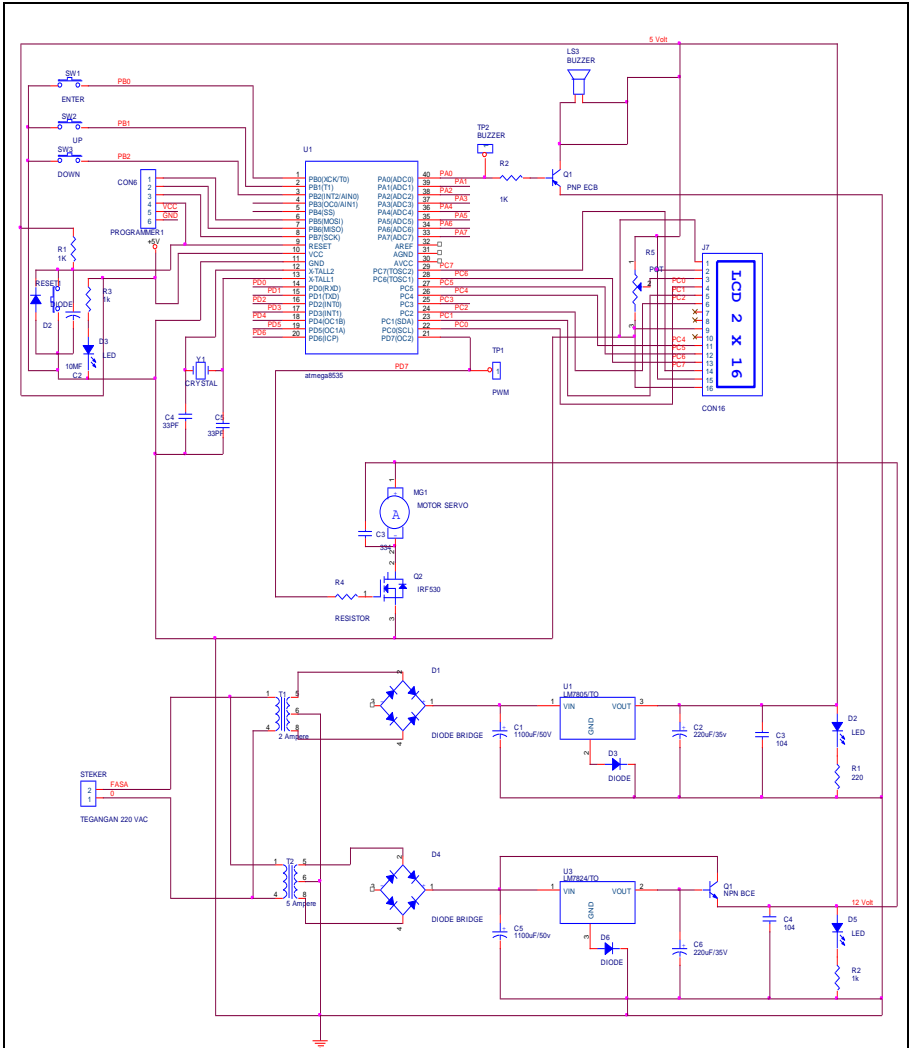
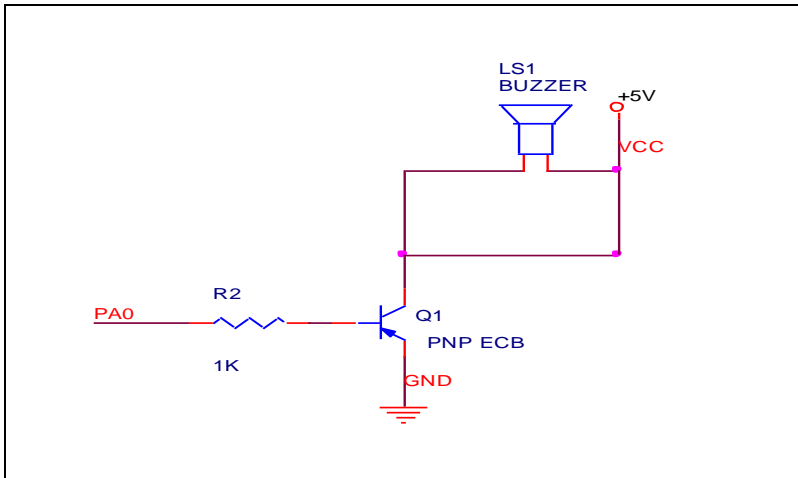


LAMPIRAN

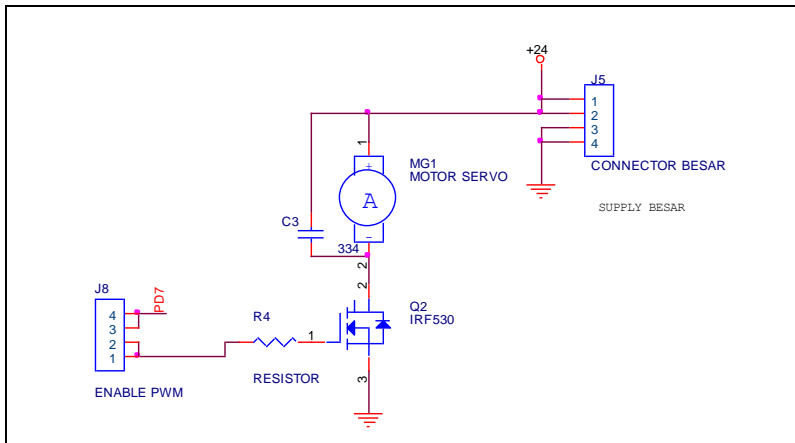
1) Rangkaian keseluruhan



2) Modul Rangkaian Buzzer



3) Modul Rangkaian Driver Motor



4) Listing Program Keseluruhan

```
/*  
*****  
This program was produced by the  
CodeWizardAVR V2.05.0 Professional  
Automatic Program Generator  
© Copyright 1998-2010 Pavel Haiduc, HP InfoTech s.r.l.  
http://www.hpinfotech.com  
Project :  
Version :  
Date   : 5/5/2014  
Author :  
Company :  
Comments:  
Chip type      : ATmega8535  
Program type   : Application  
AVR Core Clock frequency: 1.000000 MHz  
Memory model   : Small  
External RAM size : 0  
Data Stack size : 128  
*****  
*****/  
#include <mega8535.h>  
#include <delay.h>  
#include <stdlib.h>  
#define buzzer PORTA.0=1;  
// Alphanumeric LCD Module functions  
#include <alcd.h>
```

```

// Timer 0 overflow interrupt service routine
unsigned char i=1, a;
unsigned char temp1[6]; //pemilihan waktu
unsigned char temp[6];
unsigned char mikrodetik;

int detik;
int menit;

// Timer 0 overflow interrupt service routine
interrupt [TIM0_OVF] void timer0_ovf_isr(void)
{
TCNT0=0x9E;
mikrodetik++;
if (mikrodetik==10)
{
detik-- ; //untuk timer up
mikrodetik=0;
}
}

void tampil_waktu()
{

itoa(detik,temp);
lcd_gotoxy(10,1);
lcd_puts(temp);

lcd_gotoxy(9,1);
lcd_putsf(":");

itoa(menit,temp);

```

```
lcd_gotoxy(7,1);  
lcd_puts(temp);
```

```
}
```

```
void jamdigi()
```

```
{
```

```
    if(detik==59)
```

```
    {
```

```
        lcd_clear();
```

```
        detik=59;
```

```
        menit--;
```

```
    }
```

```
    if(detik<=10)
```

```
    {
```

```
        lcd_gotoxy(11,1);
```

```
        lcd_putsf(" ");
```

```
    }
```

```
    if (menit==59)
```

```
    {
```

```
        lcd_clear();
```

```
        menit=60;
```

```
    }
```

```
    if (menit<=10)
```

```
    {
```

```
        lcd_gotoxy(8,1);
```

```
        lcd_putsf(" ");
```

```
    }
```

```
}
```

```
void selesai()
```

```
{
```

```

stop:
lcd_gotoxy(0,0);
lcd_putsf("Proses Selesai");
goto stop;
}

// Declare your global variables here

void main(void)
{
// Declare your local variables here

// Input/Output Ports initialization
// Port A initialization
// Func7=In Func6=In Func5=In Func4=In Func3=In
Func2=In Func1=In Func0=Out
// State7=T State6=T State5=T State4=T State3=T
State2=T State1=T State0=1
PORTA=0x01;
DDRA=0x01;

// Port B initialization
// Func7=In Func6=In Func5=In Func4=In Func3=In
Func2=In Func1=In Func0=In
// State7=T State6=T State5=T State4=T State3=T
State2=P State1=P State0=P
PORTB=0x07;
DDRB=0x00;

// Port C initialization
// Func7=In Func6=In Func5=In Func4=In Func3=In
Func2=In Func1=In Func0=In
// State7=T State6=T State5=T State4=T State3=T
State2=T State1=T State0=T

```

```
PORTC=0x00;
DDRC=0x00;

// Port D initialization
// Func7=Out Func6=In Func5=In Func4=In Func3=In
Func2=In Func1=In Func0=In
// State7=0 State6=T State5=T State4=T State3=T
State2=T State1=T State0=T
PORTD=0x00;
DDRD=0xFF;

// Timer/Counter 0 initialization
// Clock source: System Clock
// Clock value: 0.977 kHz
// Mode: Normal top=0xFF
// OC0 output: Disconnected
TCCR0=0x00;
TCNT0=0x00;
OCR0=0x00;

// Timer/Counter 1 initialization
// Clock source: System Clock
// Clock value: Timer1 Stopped
// Mode: Normal top=0xFFFF
// OC1A output: Discon.
// OC1B output: Discon.
// Noise Canceler: Off
// Input Capture on Falling Edge
// Timer1 Overflow Interrupt: Off
// Input Capture Interrupt: Off
// Compare A Match Interrupt: Off
// Compare B Match Interrupt: Off
TCCR1A=0x00;
TCCR1B=0x00;
```

```
TCNT1H=0x00;
TCNT1L=0x00;
ICR1H=0x00;
ICR1L=0x00;
OCR1AH=0x00;
OCR1AL=0x00;
OCR1BH=0x00;
OCR1BL=0x00;

// Timer/Counter 2 initialization
// Clock source: System Clock
// Clock value: Timer2 Stopped
// Mode: Fast PWM top=0xFF
// OC2 output: Non-Inverted PWM
ASSR=0x00;
TCCR2=0;
TCNT2=0x00;
OCR2=0x00;

// External Interrupt(s) initialization
// INT0: Off
// INT1: Off
// INT2: Off
MCUCR=0x00;
MCUCSR=0x00;

// Timer(s)/Counter(s) Interrupt(s) initialization
TIMSK=0x01;

// USART initialization
// USART disabled
UCSRB=0x00;

// Analog Comparator initialization
```



```
// Analog Comparator: Off
// Analog Comparator Input Capture by Timer/Counter 1:
Off
ACSR=0x80;
SFIOR=0x00;

// ADC initialization
// ADC disabled
ADCSRA=0x00;

// SPI initialization
// SPI disabled
SPCR=0x00;

// TWI initialization
// TWI disabled
TWCR=0x00;

// Alphanumeric LCD initialization
// Connections specified in the
// Project|Configure|C Compiler|Libraries|Alphanumeric
LCD menu:
// RS - PORTC Bit 0
// RD - PORTC Bit 1
// EN - PORTC Bit 2
// D4 - PORTC Bit 4
// D5 - PORTC Bit 5
// D6 - PORTC Bit 6
// D7 - PORTC Bit 7
// Characters/line: 16

// Global enable interrupts
#asm("sei")
```

```
lcd_init(16);
lcd_clear();
lcd_gotoxy(0,0);
lcd_putsf("mini");
lcd_gotoxy(0,1);
lcd_putsf("sieve shaker");
delay_ms(500);
lcd_clear();

    lcd_gotoxy(0,0);
    lcd_putsf("Sanchia Janita K");
    lcd_gotoxy(0,1);
    lcd_putsf("P27838011034");
    delay_ms(1000);
    lcd_clear();
```

```
while (1)
{
    while(PINB.0==1)//enter
    {
        lcd_gotoxy(0,0);
        lcd_putsf("Pilih waktu");
        lcd_gotoxy(3,1);
        lcd_putsf("menit");
        itoa(i,temp1);
        lcd_gotoxy(0,1);
        lcd_puts(temp1);

        if(PINB.1==0)//UP
        {
            i=i+1;
            delay_ms(500);

            if(i>30)
```

```

    {
    i=1;
    delay_ms(500);
    lcd_clear();
    }
}

else if(PINB.2==0) //DOWN
{
    i=i-1;
    delay_ms(500);

    if(i<1)
    {
        i=30;
        delay_ms(500);
        lcd_clear();
    }
}
}
}
delay_ms(500) ;
lcd_clear();
lcd_gotoxy(0,0);
lcd_putsf("pilih mode");
delay_ms(500);

while(PINB.0==1)//enter
{
    lcd_gotoxy(0,0);
    lcd_putsf("pilih mode");
    if(PINB.1==0)//up
    {
        delay_ms(500);

```

```

a=0;
lcd_clear();
}

else if(PINB.2==0)//down
{
delay_ms(500);
a=1;
lcd_clear();
}
if (a==0)
{
lcd_gotoxy(0,1);
lcd_putsf("mode : low");
}
else if (a==1)
{
lcd_gotoxy(0,1);
lcd_putsf("mode : high");
}
}

```

```

lcd_clear();
goto proses;

```

```

proses:

```

```

if(a==0)
{
lcd_clear();
lcd_gotoxy(2,0);
lcd_putsf("mode : low");
PORTA.0=1; //buzzer ON
TCCR2=0x6D;
OCR2=40; //motor on misal mode low
}

```

```

    menit=i;    // setting timer
satu:
    lcd_gotoxy(2,0);
    lcd_putsf("mode : low");
    TCCR0=0x05;    // aktifin timer
    jamdigi();    // void pemanggilan jamdigital
    tampil_waktu();    // void pemanggilan tampil timer
pada lcd
    if(menit==0&&detik==0)
    {
        TCCR0=0x00;    //non aktifkan timer
        PORTA.0=0;    //buzzer off
        TCCR2=0x00;    //matikan motor
        selesai();    //panggil void
    }
    goto satu;
}

if(a==1)
{
    lcd_clear();
    lcd_gotoxy(2,0) ;
    lcd_putsf("mode : high");
    PORTA.0=1; //BUZZER MATI
    TCCR2=0x6D;
    OCR2=90; // misal setting mode high
    menit=i;
satu:
    lcd_gotoxy(2,0);
    lcd_putsf("mode : high");
    TCCR0=0x05;
    jamdigi();
    tampil_waktu();
    if(menit==0&&detik==0)

```

```
{
  TCCR0=0x00;
  PORTA.0=0; //buzzer ON
  TCCR2=0x00; // PWM MATI
  selesai();
}
goto satuu;

}
}
```

A. Analisis Data

1. Perhitungan data pengukuran tanpa beban

1.1 Analisa Rpm

1.1.1 Mode Low

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{2460,3+2461,2+2462,3+2462,8+2460,5}{5} \\ &= \frac{12306,5}{5} = 2461,3 \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= X_1 - \bar{X} \\ &= 2460,3 - 2461,3 \\ &= 1 \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\ &= \frac{2460,3 - 2461,3}{2460,3} \times 100\% \\ &= 0,04\% \end{aligned}$$

$$\begin{aligned} \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} \\ &= \sqrt{\frac{(2461,3-2460,3)^2 + (2461,3-2461,2)^2 + (2461,3-2462,3)^2 + (2461,3-2462,8)^2 + (2461,3-2460,5)^2}{5-1}} \\ &= 1,10 \end{aligned}$$

$$\text{e. } U_a = \frac{SD}{\sqrt{n}}$$

$$= \frac{1,106}{\sqrt{5}} = 0,49$$

1.1.2 Mode High

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{2650,5+2652,7+2653,3+2652,1+2653,4}{5} \\ &= \frac{13251,7}{5} = 2652,3 \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= X_1 - \bar{X} \\ &= 2650,5 - 2652,3 \\ &= 1,84 \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\ &= \frac{2650,5 - 2652,3}{2650,5} \times 100\% \\ &= 0,07\% \end{aligned}$$

$$\begin{aligned} \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} \\ &= \sqrt{\frac{(2652,3-2650,5)^2 + (2652,3-2652,7)^2 + (2652,3-2653,3)^2 + (2652,3-2652,1)^2 + (2652,3-2653,1)^2}{5-1}} \\ &= 1,126 \end{aligned}$$

$$\text{e. Ua} = \frac{SD}{\sqrt{n}}$$

$$= \frac{1,126}{\sqrt{5}} = 0,50$$

1.2 Analisa Waktu

1.2.1 Mode Low

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{59+59+60+60+60}{5} \\ &= \frac{298}{5} = 59,6 \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= \text{Setting Waktu} - \bar{X} \\ &= 60 - 59,6 \\ &= 0,4 \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{\text{Setting Waktu} - \bar{X}}{\text{setting waktu}} \times 100\% \\ &= \frac{60 - 59,6}{60} \times 100\% \\ &= 0,6\% \end{aligned}$$

$$\text{d. SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$= \sqrt{\frac{(59,6-59)^2+(59,6-59)^2+(59,6-60)^2+(59,6-60)^2+(59,6-60)^2}{5-1}}$$

$$= 0,54$$

$$\text{e. } U_a = \frac{SD}{\sqrt{n}}$$

$$= \frac{0,54}{\sqrt{5}} = 0,24$$

1.2.2 Mode High

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{59+59+60+60+60}{5} \\ &= \frac{298}{5} = 59,6 \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= \text{Setting Waktu} - \bar{X} \\ &= 60 - 59,6 \\ &= 0,4 \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{\text{Setting Waktu} - \bar{X}}{\text{setting waktu}} \times 100\% \\ &= \frac{60 - 59,6}{60} \times 100\% \\ &= 0,6\% \end{aligned}$$

$$\text{d. SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$= \sqrt{\frac{(59,6-59)^2+(59,6-59)^2+(59,6-60)^2+(59,6-60)^2+(59,6-60)^2}{5-1}}$$

$$= 0,54$$

$$\text{e. } U_a = \frac{SD}{\sqrt{n}}$$

$$= \frac{0,54}{\sqrt{5}} = 0,24$$

2. Perhitungan data pengukuran dengan beban

Dengan waktu 10 menit

2.1 Analisa Rpm

2.1.1 Mode Low

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{2460,3+2462,5+2460,4+2461,8+2462,5}{5} \\ &= \frac{12307,5}{5} = 2461,5 \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= X_1 - \bar{X} \\ &= 2460,3 - 2461,5 \\ &= 1,2 \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\ &= \frac{2460,3 - 2461,5}{2460,3} \times 100\% \\ &= 0,048 \% \end{aligned}$$

$$\text{d. SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$= \sqrt{\frac{(2460,3 - 2461,5)^2 + (2460,3 - 2462,5)^2 + (2460,3 - 2460,4)^2 + (2460,3 - 2461,8)^2 + (2460,3 - 2462,5)^2}{5-1}}$$

$$= 1,74$$

$$\text{e. } U_a = \frac{SD}{\sqrt{n}}$$

$$= \frac{1,74}{\sqrt{5}} = 0,78$$

2.1.2 Mode High

$$\text{a. } \bar{X} = \frac{x_1 + x_2 + x_3 + x_4 + x_5}{n}$$

$$= \frac{2656,6 + 2655,1 + 2656,5 + 2655,2 + 2660,8}{5}$$

$$= \frac{13284,2}{5} = 2656,84$$

$$\text{b. Error} = X_1 - \bar{X}$$

$$= 2656,6 - 2656,84$$

$$= 0,24$$

$$\text{c. } \% \text{ Error} = \frac{X_1 - \bar{X}}{X_1} \times 100\%$$

$$= \frac{2636,6 - 2647,84}{2636,6} \times 100\%$$

$$= 0,009 \%$$

$$\begin{aligned}
 \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} \\
 &= \sqrt{\frac{(2656,6 - 2656,84)^2 + (2655,1 - 2656,84)^2 + (2656,5 - 2656,84)^2 + (2655,2 - 2656,84)^2 + (2660,8 - 2656,84)^2}{5-1}} \\
 &= \mathbf{2,32}
 \end{aligned}$$

$$\begin{aligned}
 \text{e. Ua} &= \frac{SD}{\sqrt{n}} \\
 &= \frac{2,32}{\sqrt{5}} = \mathbf{1,04}
 \end{aligned}$$

2.2 Analisa Waktu

2.2.1 Mode Low

$$\begin{aligned}
 \text{a. } \bar{X} &= \frac{x_1 + x_2 + x_3 + x_4 + x_5}{n} \\
 &= \frac{590 + 590 + 600 + 600 + 590}{5} \\
 &= \frac{2970}{5} = \mathbf{594}
 \end{aligned}$$

$$\begin{aligned}
 \text{b. Error} &= \text{Setting Waktu} - \bar{X} \\
 &= 600 - 594 \\
 &= \mathbf{6}
 \end{aligned}$$

$$\text{c. \% Error} = \frac{\text{Setting Waktu} - \bar{X}}{\text{setting waktu}} \times 100\%$$

$$= \frac{600 - 594}{600} \times 100\%$$

$$= 1\%$$

$$d. \text{ SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$= \sqrt{\frac{(590-594)^2 + (590-594)^2 + (600-594)^2 + (600-594)^2 + (590-594)^2}{5-1}}$$

$$= 6,63$$

$$e. \text{ Ua} = \frac{SD}{\sqrt{n}}$$

$$= \frac{6,63}{\sqrt{5}} = 2,97$$

2.2.2 Mode High

$$a. \bar{X} = \frac{x_1 + x_2 + x_3 + x_4 + x_5}{n}$$

$$= \frac{590 + 590 + 600 + 600 + 590}{5}$$

$$= \frac{2970}{5} = 594$$

$$b. \text{ Error} = \text{Setting Waktu} - \bar{X}$$

$$= 600 - 594$$

$$= 6$$

$$c. \% \text{ Error} = \frac{\text{Setting Waktu} - \bar{X}}{\text{setting waktu}} \times 100\%$$

$$= \frac{600 - 594}{600} \times 100\%$$

$$\begin{aligned}
 \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} = 1\% \\
 &= \sqrt{\frac{(590-594)^2 + (590-594)^2 + (600-594)^2 + (600-594)^2 + (590-594)^2}{5-1}} \\
 &= 6,63
 \end{aligned}$$

$$\begin{aligned}
 \text{e. } U_a &= \frac{SD}{\sqrt{n}} \\
 &= \frac{6,63}{\sqrt{5}} = 2,97
 \end{aligned}$$

Dengan waktu 20 menit

2.3 Analisa Rpm

2.3.1 Mode Low

$$\begin{aligned}
 \text{a. } \bar{X} &= \frac{x_1 + x_2 + x_3 + x_4 + x_5}{n} \\
 &= \frac{2459,5 + 2460,2 + 2461,5 + 2460,7 + 2461,1}{5} \\
 &= \frac{12303}{5} = 2460,6
 \end{aligned}$$

$$\begin{aligned}
 \text{b. Error} &= X_1 - \bar{X} \\
 &= 2459,5 - 2460,6 \\
 &= 1,1
 \end{aligned}$$

$$\begin{aligned}
 \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\
 &= \frac{2459,5 - 2460,6}{2459,5} \times 100\% \\
 &= \mathbf{0,044 \%}
 \end{aligned}$$

$$\begin{aligned}
 \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} \\
 &= \\
 &= \sqrt{\frac{(2459,5 - 2460,6)^2 + (2460,2 - 2460,6)^2 + (2461,5 - 2460,6)^2 + (2460,7 - 2460,6)^2 + (2461,1 - 2460,6)^2}{5-1}} \\
 &= \mathbf{3,12}
 \end{aligned}$$

$$\begin{aligned}
 \text{e. } \bar{U}_a &= \frac{SD}{\sqrt{n}} \\
 &= \frac{3,12}{\sqrt{5}} = \mathbf{1,40}
 \end{aligned}$$

2.3.2 Mode High

$$\begin{aligned}
 \text{a. } \bar{X} &= \frac{x_1 + x_2 + x_3 + x_4 + x_5}{n} \\
 &= \frac{2654,8 + 2655,5 + 2656,3 + 2655,1 + 2654,6}{5} \\
 &= \frac{13276,3}{5} = \mathbf{2655,26}
 \end{aligned}$$

$$\text{b. Error} = X_1 - \bar{X}$$

$$\begin{aligned}
 &= 2654,8 - 2655,26 \\
 &= \mathbf{0,46}
 \end{aligned}$$

$$\begin{aligned}
 \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\
 &= \frac{2654,8 - 2655,26}{2654,8} \times 100\% \\
 &= \mathbf{0,017\%}
 \end{aligned}$$

$$\begin{aligned}
 \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} \\
 &= \\
 &= \sqrt{\frac{(2654,8 - 2655,26)^2 + (2655,5 - 2655,26)^2 + (2656,3 - 2655,26)^2 + (2655,8 - 2655,26)^2 + (2654,6 - 2655,26)^2}{5-1}} \\
 &= \mathbf{0,73}
 \end{aligned}$$

$$\begin{aligned}
 \text{e. Ua} &= \frac{SD}{\sqrt{n}} \\
 &= \frac{0,73}{\sqrt{5}} = \mathbf{0,33}
 \end{aligned}$$

2.4 Analisa Waktu

2.4.1 Mode Low

$$\begin{aligned}
 \text{a. } \bar{X} &= \frac{x_1 + x_2 + x_3 + x_4 + x_5}{n} \\
 &= \frac{1159 + 1200 + 1159 + 1158 + 1200}{5} \\
 &= \frac{5876}{5} = \mathbf{1175,2}
 \end{aligned}$$

$$\begin{aligned}
 \text{b. Error} &= X_1 - \bar{X} \\
 &= 1200 - 1175,2 \\
 &= 24,8
 \end{aligned}$$

$$\begin{aligned}
 \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\
 &= \frac{1200 - 1175,2}{1200} \times 100\% \\
 &= 2\%
 \end{aligned}$$

$$\text{d. SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$\begin{aligned}
 &= \sqrt{\frac{(1175,2-1159)^2 + (1175,2-1200)^2 + (1175,2-1159)^2 + (1175,2-1158)^2 + (1175,2-1200)^2}{5-1}} \\
 &= 22,64
 \end{aligned}$$

$$\begin{aligned}
 \text{e. Ua} &= \frac{SD}{\sqrt{n}} \\
 &= \frac{22,64}{\sqrt{5}} = 1,01
 \end{aligned}$$

2.4.2 Mode High

$$\begin{aligned}\text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{1159+1200+1159+1158+1200}{5} \\ &= \frac{5876}{5} = \mathbf{1175,2}\end{aligned}$$

$$\begin{aligned}\text{b. Error} &= X_1 - \bar{X} \\ &= 1200 - 1175,2 \\ &= \mathbf{24,8}\end{aligned}$$

$$\begin{aligned}\text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\ &= \frac{1200 - 1175,2}{1200} \times 100\% \\ &= \mathbf{2\%}\end{aligned}$$

$$\text{d. SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$\begin{aligned}&= \sqrt{\frac{(1175,2-1159)^2+(1175,2-1200)^2+(1175,2-1159)^2}{5-1} \\ &\quad + (1175,2-1158)^2+(1175,2-1200)^2} \\ &= \mathbf{22,64}\end{aligned}$$

$$\begin{aligned}\text{e. } U_a &= \frac{SD}{\sqrt{n}} \\ &= \frac{22,64}{\sqrt{5}} = \mathbf{1,01}\end{aligned}$$

Dengan waktu 30 menit

2.5 Analisa Rpm

2.5.1 Mode Low

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{2456,5+2455,1+2456,4+2458,6+2456,5}{5} \\ &= \frac{12283,1}{5} = \mathbf{2456,62} \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= X_1 - \bar{X} \\ &= 2456,5 - 2456,62 \\ &= \mathbf{0,12} \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\ &= \frac{2456,5 - 2456,62}{2456,5} \times 100\% \\ &= \mathbf{0,0048 \%} \end{aligned}$$

$$\begin{aligned} \text{d. SD} &= \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}} \\ &= \sqrt{\frac{(2456,5 - 2456,6)^2 + (2455,1 - 2456,6)^2 + (2456,4 - 2456,6)^2 + (2458,6 - 2456,6)^2 + (2456,5 - 2456,6)^2}{5-1}} \\ &= \mathbf{1,226} \end{aligned}$$

$$\text{e. Ua} = \frac{SD}{\sqrt{n}}$$

$$= \frac{1,226}{\sqrt{5}} = \mathbf{0,550}$$

2.5.2 Mode High

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{2655,6+2554,6+2656,6+2655,8+2654,1}{5} \\ &= \frac{13276,7}{5} = \mathbf{2655,3} \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= X_1 - \bar{X} \\ &= 2655,6 - 2655,3 \\ &= \mathbf{0,3} \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\ &= \frac{2655,6 - 2655,3}{2655,6} \times 100\% \\ &= \mathbf{0,01\%} \end{aligned}$$

$$\text{d. SD} = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$\begin{aligned} &= \sqrt{\frac{(2654,8 - 2655,3)^2 + (2655,5 - 2655,3)^2 + (2656,3 - 2655,3)^2 \\ &\quad + (2655,1 - 2655,3)^2 + (2654,6 - 2655,3)^2}{5-1}} \\ &= \mathbf{0,45} \end{aligned}$$

$$\begin{aligned}
 \text{e. } U_a &= \frac{SD}{\sqrt{n}} \\
 &= \frac{0,45}{\sqrt{5}} = \mathbf{0,20}
 \end{aligned}$$

2.6 Analisa Waktu

2.6.1 Mode Low

$$\begin{aligned}
 \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\
 &= \frac{1759+1759+1800+1759+1800}{5} \\
 &= \frac{8877}{5} = \mathbf{1775,4}
 \end{aligned}$$

$$\begin{aligned}
 \text{b. Error} &= X_1 - \bar{X} \\
 &= 1800 - 1775,4 \\
 &= \mathbf{24,6}
 \end{aligned}$$

$$\begin{aligned}
 \text{c. \% Error} &= \frac{x_1 - \bar{X}}{x_1} \times 100\% \\
 &= \frac{1800 - 1775,4}{1800} \times 100\% \\
 &= \mathbf{1,36 \%}
 \end{aligned}$$

$$\text{d. } SD = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$\begin{aligned}
 &= \sqrt{\frac{(1775,4-1759)^2+(1775,4-1759)^2+(1775,4-1800)^2}{5-1} + \frac{(1775,4-1759)^2+(1775,4-1800)^2}{5-1}}
 \end{aligned}$$

$$= 20,71$$

$$\begin{aligned} \text{e. } U_a &= \frac{SD}{\sqrt{n}} \\ &= \frac{20,71}{\sqrt{5}} = 9,2 \end{aligned}$$

2.6.2 Mode High

$$\begin{aligned} \text{a. } \bar{X} &= \frac{x_1+x_2+x_3+x_4+x_5}{n} \\ &= \frac{1759+1759+1800+1759+1800}{5} \\ &= \frac{8877}{5} = 1775,4 \end{aligned}$$

$$\begin{aligned} \text{b. Error} &= X_1 - \bar{X} \\ &= 1800 - 1775,4 \\ &= 24,6 \end{aligned}$$

$$\begin{aligned} \text{c. \% Error} &= \frac{X_1 - \bar{X}}{X_1} \times 100\% \\ &= \frac{1800 - 1775,4}{1800} \times 100\% \\ &= 1,36\% \end{aligned}$$

$$\text{d. } SD = \sqrt{\frac{(\sum x - \bar{X})^2}{n-1}}$$

$$= \sqrt{\frac{(1775,4-1759)^2+(1775,4-1759)^2+(1775,4-1800)^2+(1775,4-1759)^2+(1775,4-1800)^2}{5-1}}$$
$$= 20,71$$

e. $U_a = \frac{SD}{\sqrt{n}}$

$$= \frac{20,71}{\sqrt{5}} = 9,2$$